1	The opinion in support of the decision being
2	entered today was not written for publication
3	and is not binding precedent of the Board.
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7	UNITED STATES PATENT AND TRADEMARK OFFICE
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9	
10	BEFORE THE BOARD OF PATENT APPEALS
11	AND INTERFERENCES
12	
13	
14	Ex parte TIMOTHY G. OFFERLE,
15	CRAIG H. STEPHAN and GREGORY P. BROWN
16	
17	1 200 - 0 5 -
18	Appeal 2007-0677
19	Application 10/708,677
20	Technology Center 3600
21	
22	Decided Mend 22, 2007
23	Decided: March 22, 2007
24 25	
25 26	Before TERRY J. OWENS, STUART S. LEVY, and ROBERT E. NAPPI
27 27	Administrative Patent Judges.
28	nammstrative I atem Juages.
29	NAPPI, Administrative Patent Judge.
30	1411 1, Hammish anve I alem baage.
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32	DECISION ON APPEAL
33	
34	This is a decision on appeal under 35 U.S.C. § 6(b) of the final
35	rejection of claims 1 through 30. For the reasons stated infra we will not
36	sustain the Examiner's rejection of these claims.

1		INVENTION	
2	The invention	is directed to a system to de	termine and predict the
4	position of a trailer re	elative to a vehicle. The syst	em then displays the
	•	•	
5	trailer's current and p	redicted position to the veh	icle's driver to assist in
6	controlling the direct	ion of the trailer relative to	the vehicle. See paragraph
7	0008 of Appellants' s	specification. Claim 1 repre	sentative of the invention
8	and reproduced below	v:	
9	1. A met	hod for use in a vehicle con	nprising;
10	sensing a	a current position of a trailer	r relative to the vehicle;
11		ing a vehicle steering whee	•
12		ing a predicted position of	
13	<u>-</u>	n and the steering wheel ang	
14		ng within the vehicle the cur	-
15	predicted posit	ion of the trailer relative to	the vehicle.
16		DEEEDENGEO	
17 18		REFERENCES	
10 19	The references	relied upon by the Examine	ar are:
20	The references	reflect upon by the Examine	arc.
21	Yoshioka	US 5,461,357	Oct. 24, 1995
22	Gerum	US 5,747,683	May 05, 1998
23	Deng	US 6,292,094	Sep. 18, 2001
24	Mizusawa	US 2002/0145663 A1	Oct. 10, 2002
25	Hrazdera	US 6,704,637 B1	Mar. 09, 2004
26		(Effectively fil	ed Jun. 10, 2002)
27			
28			_
29		REJECTION AT ISSU	E
30	Claims 1 through	gh 4, 11 through 27, 29 and	30 stand rejected under

1 35 U.S.C. § 103 (a) as being unpatentable over Deng or Gerum in view of Mizusawa. The Examiner's rejection is set forth on pages 3 and 4 of the 2 Answer. Claims 5 through 10 and 18 stand rejected under 35 U.S.C. 3 § 103(a) as being unpatentable over Deng or Gerum in view of Mizusawa 4 and Hrazdera. The Examiner's rejection is set forth on pages 5 and 6 of the 5 Answer. Claim 28 stands rejected under 35 U.S.C. § 103(a) as being 6 7 unpatentable over Deng or Gerum in view of Mizusawa and Yoshioka. The 8 Examiner's rejection is set forth on page 6 of the Answer. Throughout the opinion we make reference to the Brief and Reply Brief (received August 9 12, 2005 and August 1, 2006 respectively), and the Answer (mailed June 2, 10 2006) for the respective details thereof. 11 12 **ISSUES** Appellants contend that the Examiner's rejection of independent 13 claims 1, 12 and 21 under 35 U.S.C. § 103(a) is in error. Appellants argue 14 that both Deng and Gerum teach systems which calculate the current 15 16 position of the trailer but that they do not teach determining a predicted 17 position of a trailer. Further, Appellants argue that in combination with Mizusawa, the references do not teach displaying both the current and 18 19 predicted position of the trailer. 20 The Examiner asserts that the rejection is proper. The Examiner, on page 7 of the Answer, equates the "desired hitch angle" of Deng with the 21 claimed predicted position. The Examiner also equates the determination of 22 a jackknife condition in Gerum with the claimed predicted position. 23

1 Thus, the question before us is whether either Deng or Gerum in 2 combination with Mizusawa teach or suggest determining a predicted position as claimed and displaying the predicted position of the trailer 3 relative to the vehicle? 4 FINDINGS OF FACT. 5 Gerum teaches a system for stabilizing a vehicle with a trailer. See 6 7 abstract. The system monitors several parameters of the vehicle such as steering angle, brake pressure and air suspension pressure. See column 5, 11. 8 41-55. These parameters are used as input to a model which estimates 9 10 among other things the hitch angle and rate of change of hitch angle. See column 5, ll. 60-65. These estimates are then used when the vehicle is in a 11 braking condition to individually adjust the braking force applied to the left 12 13 or right side rear wheels of the vehicle. See abstract and column 10, ll. 18-33. By applying an unequal brake force, the system acts to stabilize the 14 15 vehicle, reducing the chances of a jackknife or other uncontrolled vehicle conditions. See abstract. We do not find that the model determines a 16 predicted position, but rather the current position. We do not find that 17 18 Gerum teaches predicting a jackknife condition but rather creating a stabilizing effect assumedly to preclude a jackknife condition. 19 20 Deng teaches a system for assisting a driver backing up a vehicle which has four wheel steering and is towing a trailer. See abstract. The 21 22 system adjusts the rear wheel steering angle to guide the trailer to the

¹ In a four wheel steering system the rear wheels may turn either with or counter to the front wheels.

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- 1 location selected by the driver. The driver identifies the intended position
- 2 of the trailer to the system by positioning the steering wheel of the vehicle
- 3 as if they were backing the vehicle up without a trailer.² The system
- 4 monitors the steering wheel position and calculates the intended position.
- 5 See column 2, l. 64 to column 3, l. 3. The system then calculates the proper
- 6 angle for the rear wheels to steer the trailer to the intended position. If the
- 7 rear wheels can be turned to this angle the driver continues to back up,
- 8 steering as if there was no trailer and the system will adjust the rear wheels
- 9 to locate the trailer. See column 3, lines 7-13. If the rear wheels can not be
- turned to this angle, the driver is instructed to counter steer and the system
- 11 controls the steering of the rear wheels to position the trailer in the intended
- position. Column 3 ll. 13-22. Deng is silent as to whether the driver is
- 13 advised of the systems' status visually or audibly, although the driver
- 14 advisor, item 42 is depicted as a speaker.
- Mizusawa teaches a system to assist a driver in backing up a vehicle
- to meet a trailer. See abstract. The system makes use of camera images
- 17 which are enhanced and displayed to the driver. See paragraph 0016. The
- images present a view of the rear of the vehicle and include an indicator of
- where the hitch is on the vehicle and is used in aligning the hitches of the
- vehicle and trailer when coupling the two. See paragraph 0018.

² When backing up with a trailer in a two wheel steering system the driver has to counter steer to guide the trailer, i.e. when backing up with a trailer you turn the steering wheel opposite the direction you would steer as if you did not have a trailer.

1	PRINCIPLES OF LAW		
2	Office personnel must rely on Appellants' disclosure to properly		
3	determine the meaning of the terms used in the claims. Markman v.		
4	Westview Instruments, Inc., 52 F3d 967, 980, 34 USPQ2d 1321, 1330 (Fed.		
5	Cir. 1995). "[I]nterpreting what is meant by a word in a claim 'is not to be		
6	confused with adding an extraneous limitation appearing in the		
7	specification, which is improper." (emphasis original) In re Cruciferous		
8	Sprout Litigation, 301 F.3d 1343, 1348, 64 USPQ2d 1202, 1205, (Fed. Cir.		
9	2002) (citing Intervet America Inc v. Kee-Vet Laboratories Inc., 12		
10	USPQ2d 1474, 1476 (Fed. Cir. 1989). It is the burden of the Examiner to		
11	establish why one having ordinary skill in the art would have been led to the		
12	claimed invention by the express teachings or suggestions found in the prior		
13	art, or by the implications contained in such teachings or suggestions. In re		
14	Sernaker, 702 F.2d 989, 995, 217 USPQ 1, 6 (Fed. Cir. 1983).		
15			
16	ANALYSIS		
17	Independent claim 1 recites "determining a predicted position of a		
18	trailer based upon the current position and the steering wheel alignment;		
19	and displaying within the vehicle, the current position and the predicted		
20	position of the trailer relative to the vehicle." Independent claim 12		
21	includes similar limitations. Independent claim 21 recites "a controller		
22	coupled to the trailer position signal display, and steering wheel angle		
23	sensor, said controller displaying a predicted path of the trailer in response		
24	to the position signal." Thus, each of the independent claims recites		

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displaying a predicted position or path of the trailer and that the predicted 1 position is calculated based upon the current position and wheel angle. The 2 display's other predicted positions are shown in Appellants' figure 20 and 3 discussed in paragraph 0124. 4 As discussed *supra* we find that Gerum teaches a system for 5 stabilizing a vehicle with a trailer which uses a model of the vehicle 6 dynamics. However, we do not find that Gerum teaches that the model 7 determines a predicted position, but rather the current position. We find 8 that Deng teaches a system to assist a driver backing up a vehicle with four 9 wheel steering and a trailer. The system calculates the steering angles 10 needed to place the trailer in an intended position. The intended position of 11 the trailer is input to the system by the user's control of the steering wheel. 12 While the system performs calculations to interpret the intended position 13 from the user's control of the steering wheel, this is not a predicted position, 14 but rather a position input by the user. Finally, we find that Mizusawa 15 discloses a system to provide and display a rear view of the vehicle. We do 16 not find that Mizusawa discloses calculating a predicted position. Thus, we 17 18 do not find that Gerum, Deng, and Mizusawa determine a predicted position as recited in the claims, nor do we find that the combination of the 19 20 references teach or suggest displaying a predicted position as claimed. 21 22

1	CONCLUSION
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3	We consider the Examiner's rejection of claims 1 through 30 under
4	35 U.S.C. § 103(a) to be in error as we do not find that the combination of
5	the combination of Deng or Gerum with Mizusawa teach or suggest the
6	limitations in independent claims 1, 12, and 21. The Examiner has not
7	asserted, nor do we find that Hrazdera or Yoshioka, the references applied
8	against claims 5 through 10, 18 and 28, make up for the noted deficiencies
9	in the rejection of independent claims 1, 12 and 21. Accordingly we will
10	not sustain the Examiner's rejection of claims 35 U.S.C. § 103 (a) of claims
11	1 through 30.
12	ORDER
13 14	For the forgoing reasons, we will not sustain the Examiner's
15	rejections, under 35 U.S.C. § 103. The decision of the Examiner is reversed
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17	REVERSED
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23	
24	
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